Autonics

LCD Display PID Temperature Controller TX4S SERIES

INSTRUCTION MANUAL

(€ ,¶1, 1]



Thank you for choosing our Autonics product. Please read the following safety considerations before use.

■ Safety Considerations

**Please observe all safety considerations for safe and proper product operation to avoid hazards. *Safety considerations are categorized as follows.

▲Warning Failure to follow these instructions may result in serious injury or death

▲Caution Failure to follow these instructions may result in personal injury or product damage. *The symbols used on the product and instruction manual represent the following

▲ symbol represents caution due to special circumstances in which hazards may occur.

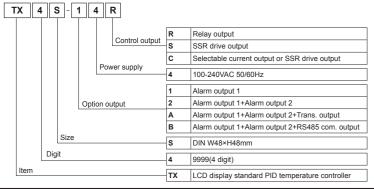
▲ Warning

- 1. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in fire, personal injury, or economic loss
- 2. Install on a device panel to use.
 Failure to follow this instruction may result in electric shock or fire
- 3. Do not connect, repair, or inspect the unit while connected to a power source.
- Failure to follow this instruction may result in electric shock or fire 4. Check 'Connections' before wiring.
- Failure to follow this instruction may result in fire
- Do not disassemble or modify the unit.
 Failure to follow this instruction may result in electric shock or fire

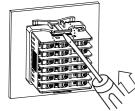
▲ Caution

- 1. When connecting the power input and relay output, use AWG 20(0.50mm²) cable or over and tighten the terminal screw with a tightening torque of 0.74~0.90N·m.
 When connecting the sensor input and communication cable without dedicated cable, use AWG 28~16
- cable and tighten the terminal screw with a tightening torque of 0.74~0.90N·m. Failure to follow this instruction may result in fire or malfunction due to contact failure 2. Use the unit within the rated specifications.
- Failure to follow this instruction may result in fire or product damage
- 3. Use dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in electric shock or fire.
- 4. Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present. Failure to follow this instruction may result in fire or explosion
- 5. Keep metal chip, dust, and wire residue from flowing into the unit.
 Failure to follow this instruction may result in fire or product damage.

Ordering Information



Installation



Mount the unit on the panel. Push the bracket with

The above specifications are subject to change and some models may be discontinued

»Be sure to follow cautions written in the instruction manual and the technical descriptions (catalog, homepage).

E Chacifications

Series		TX4S					
Power sup	ply	100-240VAC~ 50/60Hz					
Allowable voltage range		90 to 110% of rated voltage					
Power con	sumption	Max. 8VA					
Display me	ethod	11 segments (PV: white, SV: green), other display (yellow) with LCD method ^{x1}					
Character PV(W×H)		6.9×15.3mm					
size	SV(W×H)	4.1×9.2mm					
Input type	RTD	DPt100Ω, Cu50Ω (permissible line resistance max. $5Ω$)					
iliput type	TC	K(CA), J(IC), L(IC), T(CC), R(PR), S(PR)					
Display	RTD	 ◆At room temperature (23°C±5°C): (PV ±0.3% or ±1°C, select the higher one) ±1digi 					
accuracy*	TC	Out of room temperature: (PV ±0.5% or ±2°C, select the higher one) ±1digit					
Control	Relay	250VAC~ 3A 1a					
output	SSR	Max. 12VDC ± 2V 20mA					
output	Current	DC4-20mA or DC0-20mA (load resistance max. 500Ω)					
Option	Alarm output	AL1, AL2 Relay: 250VAC~ 3A 1a					
output	Trans. output	DC4-20mA (load resistance max. 500Ω, output accuracy: ±0.3%F.S.)					
output	Com. output	RS485 Communication output (Modbus RTU method)					
Control me	ethod	ON/OFF control, P, PI, PD, PID control					
Hysteresis		1 to 100°C/°F (0.1 to 50.0°C/°F) variable					
Proportion	al band(P)	0.1 to 999.9°C/°F					
Integral tin	ne(I)	0 to 9999 sec					
Derivative	time(D)	0 to 9999 sec					
Control pe	riod(T)	0.5 to 120.0 sec					
Manual res	set	0.0 to 100.0%					
Sampling	period	50ms					
Dielectric s	strength	3,000VAC 50/60Hz for 1 min (between all terminals and case)					
Vibration		0.75mm amplitude at frequency 5 to 55Hz (for 1 min)in each X, Y, Z direction for 2 hours					
Relay	Mechanical	OUT, AL1/2: Min. 5,000,000 operations					
life cycle	Electrical	OUT, AL1/2: Min. 200,000 (250VAC 3A resistance load)					
Insulation	resistance	Min. 100MΩ (at 500VDC megger)					
Noise resis	stance	Square shaped noise by noise simulator (pulse width 1µs) ±2kV R-phase, S-phase					
Memory re	tention	Approx. 10 years (non-volatile semiconductor memory type)					
Environ-	Ambient temp.	-10 to 50°C, storage: -20 to 60°C					
ment	Ambient humi.	35 to 85%RH, storage: 35 to 85%RH					
Protection	structure	IP50 (front panel, IEC standards)					
Insulation	type	Double insulation (mark: : , dielectric strength between all terminals and case: 3kV					
Approval		∅ 20 (€, 3)					
Weight**3		Approx. 135.2g (approx. 85.2g)					
½1. Whon	ueina the unit	at low temperature (below 0°C), display cycle is slow.					

When using the unit at low temperature (below 0°C), display cycle is slow.

Control output operates normally.

At room temperature(23°C±5°C)

*TC R(PR), S(PR), below 200°C; (PV ±0.5% or ±3°C, select the higher one) ±1 digit , over 200°C: (PV \pm 0.5% or \pm 2°C, select the higher one) \pm 1 digit • TC L(IC), RTD Cu50 Ω : (PV \pm 0.5% or \pm 2°C, select the higher one) \pm 1 digit

• 1C L(IC), RTD Cu50LY (PV ±0.5% of ±2°C, select the higher one) ±1 digit

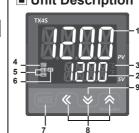
Out of room temperature range

• TC R(PR), S(PR): (PV ±1.0% or ±5°C, select the higher one) ±1 digit

• TC L(IC), RTD Cu50\(\text{L}\) (PV ±0.5% or ±3°C, select the higher one) ±1 digit

※3. The weight includes packaging. The weight in parentheses is for unit only.

※Environment resistance is rated at no freezing or condensation.



■ Unit Description 1. Measured value (PV) component:

RUN mode: Displays current measured value (PV). SETTING mode: Displays parameters.

Setting value (SV) display component RUN mode: Displays setting value(SV) SETTING mode: Displays setting value of parameter.

mperature unit(°C/°F) indicator

Displays the set temperature unit as temperature unit [UNI E] of parameter 2 group. parameter 2 group.

4. Control output (OUT1) indicator: Turns ON while control output is ON.

XTurns ON when MV is over 3.0% at cycle/phase control of SSR drive

output method 5. Alarm output (AL1, AL2) indicator:

Turns ON when the corresponding alarm output turns ON. Auto-tuning indicator:
 Flashes during auto-tuning every 1 sec.

7. MODE key: Enters parameter group, returns to RUN mode, moves parameters,

and saves the setting value.

8. Setting value adjutment key: Enters SV setting mode and move digits.

9. Digital input key: Press the 🔄 keys for 3 sec to execute the digital input key functions which is set at digital input key[dl - //]of parameter 2 group (RUN/STOP clear alarm output, auto-tuning).

10. PC loader port: It is for serial communication to set parameter and monitoring b DAQMaster installed in PC. Use this for connection EXT-US (converter cable, sold separately) + SCM-US (USB to Serial converter, sold separately).

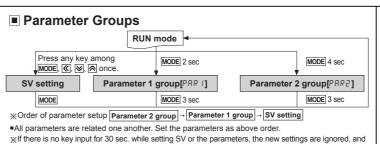
Connection

*Shaded terminals is standard model

SSR 12VDC±2V 20mA I	Max.								
Current DC0/4-20mA Load 500ΩMax.	1		13	7	AL1 OUT: 250VAC 3A 1a				
Relay 250VAC 3A 1a RESISTIVE LOAD	2		14	8	RESISTIVE LOAD AL2 OUT: 250VAC 3A 1a	※Use	teminals of siz	e specifie	ed below.
₽ ↑ ₽₹	3 :7	(mA) RS485(A+)	15	9	RESISTIVE LOAD			а	b
(V) (mA)	4	T-	46	10	A B		[O]ta a	Min. 3.0mm	Max. 5.8mm
	5	Communication Output	17	11	4 B/√ 4 +	<r< td=""><td>ound></td><td>5.011111</td><td>3.0111111</td></r<>	ound>	5.011111	3.0111111
SOURCE 100-240VAC	6	Transfer Output DC4-20mA	18	12	B' - RTD TC SENSOR	<f< td=""><td>orked></td><td>Min. 3.0mm</td><td>Max. 5.8mm</td></f<>	orked>	Min. 3.0mm	Max. 5.8mm
50/60Hz 8VA									

Input Type And Range

Input type	Input type		Display	Input range(°C)	Input range(°F)
	K(CA)	1	KERH	-50 to 1200	-58 to 2192
	K(CA)	0.1	KERL	-50.0 to 999.9	-58.0 to 999.9
	J(IC)	1	JI E.H	-30 to 800	-22 to 1472
	J(IC)	0.1	JI C.L	-30.0 to 800.0	-22.0 to 999.9
Thermocouple	L(IC)	1	LI E.H	-40 to 800	-40 to 1472
Thermocoupie		0.1	LT E.L	-40.0 to 800.0	-40.0 to 999.9
	T(CC)	1	FEEH	-50 to 400	-58 to 752
	1(00)	0.1	F C C.L	-50.0 to 400.0	-58.0 to 752.0
	R(PR)	1	RPR	0 to 1700	32 to 3092
	S(PR)	1	SPR	0 to 1700	32 to 3092
	DPt 100Ω	1	dPE,H	-100 to 400	-148 to 752
RTD	DP1 10012	0.1	dPE.L	-100.0 to 400.0	-148.0 to 752.0
	Cu50Ω	1	ЕИБН	-50 to 200	-58 to 392
	Cusuu	0.1	E U S.L	`-50.0 to 200.0	-58.0 to 392.0



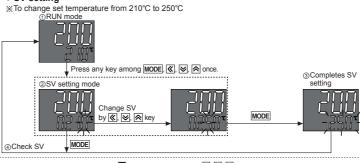
the unit will return to RUN mode with previous settings. *When returning to RUN mode by holding the MODE key for over 3 sec, press the MODE key within 1 sec to

re-enter the first parameter of previous parameter group. χ Hold the $\sqrt[4]{+}$ keys for 5 sec in RUN mode, to enter re-set parameter menu. Select ' \pm E5' and all

SV setting

parameters are reset as factory default.

PRR I

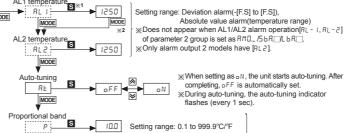


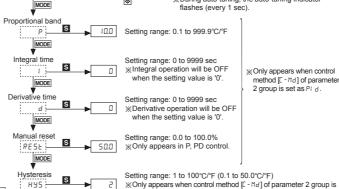
• Parameter 1 group

1: **S: Press any key among **(C) (D) (A)****2: Press the **(MODE)** key once after changing the setting value, to save the setting value and move to the next parameter

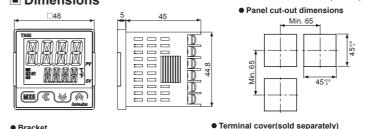
**Hold the MODE key for 3 sec to save the setting value and return to RUN mode MODE 2 sec after changing the setting value. X: Dotted parameters may not appear by model type or other parameter

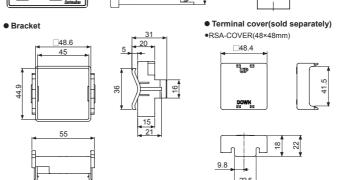
Setting range: Deviation alarm(-[F.S] to [F.S]),

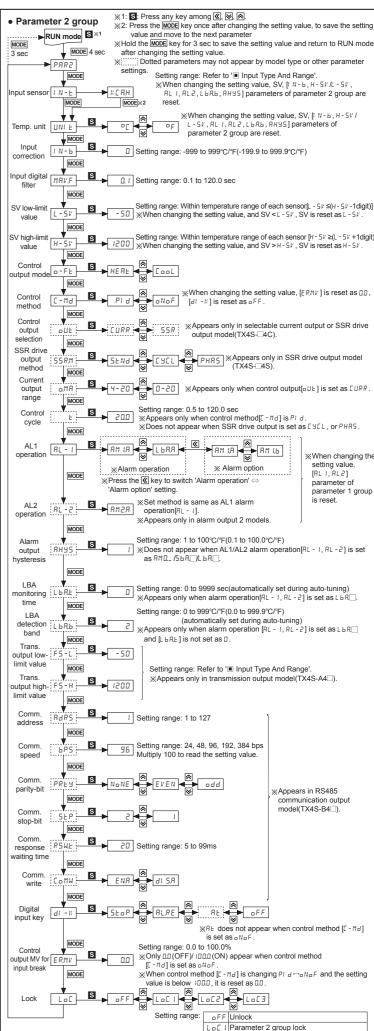




(unit:mm) Dimensions Panel cut-out dimensions

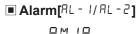






Lo[2] Parameter 1,2 group lock

Lo[3] Parameter 1,2 group, SV setting lock



AM I.A option

Set both alarm operation and alarm option by combining. Each alarm operates individually in two alarm output models. When the current temperature is out of alarm range, alarm clears automatically. If alarm option is alarm latch or alarm latch and standby sequence 1/2, press digital input key(避HÃ) 3 sec, digital input key(-#:) of parameter 2 group set as RLRE), or turn OFF the power and turn ON to clear alarm.

Alarm operation

Mode	Name	Alarm operation	Description
AMO	-	-	No alarm output
Am L□	Deviation high-limit alarm	OFF	If deviation between PV and SV as high-limit is higher than set value of deviation temperature, the alarm output will be ON.
Am 2.	Deviation low-limit alarm	ON ↑ H ↓ OFF	low-limit is higher than set value of deviation temperature, the alarm
Am 3.	Deviation high/low- limit alarm	ON THU OFF UHTON ON THU OFF UHTON ON THU OFF ON THU ON ON ON THU ON THU ON ON ON ON ON ON ON ON ON ON	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be ON.
ЯМЧ.□	Deviation high/low- limit reserve alarm	OFF H ON H OFF DV SV PV 90°C 100°C 110°C High, Low-limit deviation: Set as 10°C	If deviation between PV and SV as high/low-limit is higher than set value of deviation temperature, the alarm output will be OFF.
AM 5.□	Absolute value high limit alarm	OFF	If PV is higher than the absolute value, the output will be ON.
Am 6.	Absolute value low limit alarm	ON THU OFF	If PV is lower than the absolute value, the output will be ON.
56R.□	Sensor break alarm	-	It will be ON when it detects sensor disconnection.
L b R.□	Loop break	_	It will be ON when it detects loop

※ H: Alarm output hysteresis [₱₦Ყ5]

Alarm option

ı	Option	Name	Description
	ям 🗆 я	Standard alarm	If it is an alarm condition, alarm output is ON. If it is a clear alarm condition, alarm output is OFF.
	ЯМШ.Ь	Alarm latch	If it is an alarm condition, alarm output is ON and maintains ON status. (Alarm output HOLD)
	AM□.E	Standby sequence 1	First alarm condition is ignored and from second alarm condition, standard alarm operates. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, standard alarm operates.
	AM□.d	Alarm latch and standby sequence 1	If it is an alarm condition, it operates both alarm latch and standby sequence. When power is supplied and it is an alarm condition, this first alarm condition is ignored and from the second alarm condition, alarm latch operates.
	AM□.E	Standby sequence 2	First alarm condition is ignored and from second alarm condition, standard alarm operates. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, standard alarm operates.
	AM□.F	Alarm latch and standby sequence 2	Basic operation is same as alarm latch and standby sequence1. It operates not only by power ON/OFF, but also alarm setting value, or alarm option changing. When re-applied standby sequence and if it is alarm condition, alarm output does not turn ON. After clearing alarm condition, alarm latch operates.

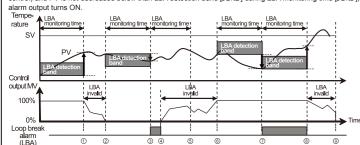
**Condition of re-applied standby sequence for standby sequence 1, alarm latch and standby sequence 1: Power ON Condition of re-applied standby sequence for standby sequence 2, alarm latch and standby sequence 2; Power ON. changing set temperature, alarm temperature [RL 1, RL 2] or alarm operation [RL - 1, RL - 2], switching STOP mode to RUN mode.

Sensor break alarm

The function that alarm output will be ON when sensor is not connected or when sensor's disconnection is detected during temperature controlling. You can check whether the sensor is connected with buzzer or other units using alarm output contact. It is selectable between standard alarm [568,81] or alarm latch [568,61].

Loop break alarm(LBA)

It checks control loop and outputs alarm by temperature change of the subject. For heating control(cooling control), when control output MV is 100%(0% for cooling control) and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], or when control output MV is 0%(100% for cooling control) and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b Rb].



(LDA)	
Start control to ①	When control output MV is 100%, PV is increased over than LBA detection band [ኒ եብե] during LBA monitoring time [ኒ եብե].
1) to 2	The status of changing control output MV (LBA monitoring time is reset.)
2 to 3	When control output MV is 0% and PV is not decreased below than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], loop break alarm (LBA) turns ON after LBA monitoring time.
3 to 4	Control output MV is 0% and loop break alarm (LBA) turns and maintains ON.
4 to 6	The status of changing control output MV (LBA monitoring time is reset.)
6 to 7	When control output MV is 100% and PV is not increased over than LBA detection band [L b Rb] during LBA monitoring time [L b Rb], loop break alarm (LBA) turns ON after LBA monitoring time.
7 to 8	When control output MV is 100% and PV is increased over than LBA detection band [L bRb] during LBA monitoring time [L bRb], loop break alarm (LBA) turns OFF after LBA monitoring time.
8 to 9	The status of changing control output MV (LBA monitoring time is reset.)

When executing auto-tuning, LBA detection band[LbAb] and LBA monitoring time are automatically set based on auto tuning value. When alarm operation mode [RL - I, RL - 2] is set as loop break alarm(LBA)[LbR□], LBA detection band [L bRb] and LBA monitoring time [L bRb] parameter is displayed.

Functions

1. Input correction[| N-b]

Controller itself does not have errors but there may be error by external input temperature sensor. This function is for correcting this error.

Ex) If actual temperature is 80°C but controller displays 78°C, set input correction value [1 N-b] as '2' and

controller displays 80°C.

As the result of input correction, if current temperature value (PV) is over each temperature range of input sensor it displays HHHH or LLLL

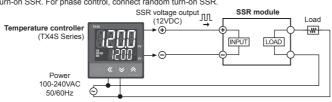
2. Input digital filter[MRV.F]

If current temperature (PV) is fluctuating repeatedly by rapid change of input signal, it reflects to MV and stable control is impossible. Therefore, digital filter function stabilizes current temperature value. For example, set input digital filter value as 0.4 sec, and it applies digital filter to input values during 0.4 sec and displays these values. Current temperature may be different by actual input value.

and linear output(cycle control and phase control)

- 3. SSR drive output method (SSRP function)[55R/1]

 · SSRP function is selectable one of standard ON/OFF control, cycle control, phase control by utilizing standard SSR drive output.
- This function parameter appears only in SSR drive output model (TX4S-□4S).
- Realizing high accuracy and cost effective temperature control with both current output (4-20mA)
- Select one of standard ON/OFF control [5ENd], cycle control [EYEL], phase control [PHR5] at 55RM parameter of parameter 2 group. For cycle control, connect a zero cross turn-on SSR or random turn-on SSR. For phase control, connect random turn-on SSR.



*When selecting cycle or phase control mode, the power supply for a load and a temperature controller must be the same.

※Control cycle[E] is able to set only when control method[E - Md] of parameter group 2 is set as Pl d and SSR.

drive output method [55R/t] is set as 5E/td. Kin case of selectable current output or SSR drive output model(TX4S-□4C), this parameter does not appear Standard ON/OFF control by SSR is only available.

1)Standard ON/OFF control [5 t N d] Controls ON (100% output)/OFF (0% output) as same as standard relay output.

2)Cycle control [E 4E L]

Controls the load by repeating output ON / OFF according to the rate of output within setting cycle based on certain period (50-cycle) Control accuracy is almost the same with phase control's. This control has improved ON/

OFF noise than phase control's due to zero cross type which turns ON/OFF at zero point of AC. 3)Phase control [PHR5] Controls the load by controlling the

phase within AC half cycle. Serial control is available. Must use random turn-on SSR for

4. Current output range[oMR]

In case of selectable current output or SSR drive output model(TX4S-[4C]), when control output [aUE] parameter 2 group is set as [URR], you can select high/low-limit range, 4-20mA [4-20] or 0-20mA [0-20] of current output.

5. Hysteresis[H95]

Set interval between ON and OFF of control output for ON/OFF

olf hysteresis is too narrow, hunting(oscillation, chattering) could

occur due to external noise.

•In case of ON / OFF control mode, even if PV reaches stable status, there still occurs hunting. It could be due to hysteresis [H95] setting value, load's response characteristics or sensor's location. In order to reduce hunting to a minimum, it is required to take into following factors consideration when designing temp. controlling; proper Hysteresis [H95], heater's capacity, thermal

characteristics, sensor's response and location. 6. Manual reset[RE5b]

When selecting P/PD control mode, certain temperature difference exists even after PV reaches stable status because heater's rising and falling time is inconsistent due to thermal characteristics of controlled objects, such as heat capacity, heater capacity. This temperature difference is called offset and manual reset IPE5E1 function is to set/

When PV and SV are equal, reset value is 50.0%. After control is stable. PV is lower than SV, reset value is over 50.0% or PV is higher than SV, reset value is below 50.0%. 7. Digital input key(+ 3 sec)[d1 - 16]

Manual reset [₱₤5₺] by control result Set below 50.0 as reset value Offset Offset Set over 50.0 as reset value

50 Cycle

Heating operation

Parameter		Operation					
OFF	oFF	It does not use digital input key function.					
RUN/STOP	StoP	Pauses control output. Auxiliary output (except loop break alarm, sensor break alarm) except Control output operates as setting. Hold the digital input keys for 3 sec to restart to the digital input key (t: over 3 sec) RUN STOP RUN STOP RUN					
Clear alarm	ALRE	Clears alarm output by force. (only when alarm option is alarm latch, or alarm latch and standby sequence 1/2.) This function is applied when present value is out of alarm operation range but alarm output is ON. Alarm operates normally right after clearing alarm.					
Auto-tuning	ЯĿ	Starts/Stops auto-tuning. This function is same as auto-tuning[RE] of parameter 1 group. (You can start auto-tuning [RE] of parameter 1 group and stop it by digital input key.) \mathbb{X} This parameter RE appears only when control method [$\mathbb{C} \cap \mathcal{H}d$] parameter 2 group is set as PId . When control method [$\mathbb{C} \cap \mathcal{H}d$] parameter 2 group is set as PId .					

8. Control output MV for input break[ERMV]

When control method[[- Md] of parameter 2 group is set as a No.F. set control output MV as fift (OFF) or IDDD (ON). When control method[[- Md] is set as PI d, setting range for control output MV is DD to IDDD.

Comprehensive Device Management Program[DAQMaster]

DAQMaster is a comprehensive device management software for setting parameters and monitoring

processes. DAGMaster can be downloaded from our web site at www.autonics.com.					
Item	Minimum specifications				
System	IBM PC compatible computer with Pentium III or above				
Operations	Vindows 98/NT/XP/Vista/7/8/10				
Memory	256MB+				
Hard disk	1GB+ of available hard disk space				
VGA	Resolution: 1024×768 or higher				
Others	RS232C serial port (9-pin), USB port				

■ RS485 Communication Output

Applicable for models with RS485 communication output through option output(TX4S-B4\(\)). Please refer to '
Ordering Information'.

1. Communication Specifications

Com. protocol	Modbus RTU	Com. speed	2400, 4800, 9600, 19200,
Applied standard	EIA RS485	Com. speed	38400 bps
Max. connections	31 units(address: 1 to 99)	Start-bit	1-bit fixed
Com. method	2-wire half duplex	Data-bit	8-bit fixed
Synchronization method	Asynchronous	Parity-bit	None, Even, Odd
Com. distance	Within 800m	Stop-bit	1, 2Bit
Com. response time	5 to 99ms		

2. Modbus Mapping Table

2-1. Read Coil Status (Func 01) / Force Single Coil (Func 05) [Func: 01/05, R/W: R/W]

No.(Address)	Туре		Description	Setting/Display range	Unit	Default
000001(0000)	RUN/STOP	Related	Control output run/stop	0: RUN 1: 5toP	-	StoP
000002(0001)	AT	coil,	Auto-tuning run/stop	0: off 1: oN	-	oFF
000003(0003)	Alarm Reset	variable	Alarm output clear	0: oFF 1: oN	-	oFF
000004 to 000050	Reserved					

2-2. Read Discrete Inputs(Func 02) [Func: 02, R/W: R]

	No.(Address)	Туре		Description	Setting/Display range	Unit	Default
	100001(0000)	°C indicator		Unit indicator	0: OFF 1: ON	-	-
الر	100002(0001)	°F indicator		Unit indicator	0: OFF 1: ON	-	-
′II	100003(0002)	OUT indicator	Front	Control output indicator	0: OFF 1: ON	-	-
\dashv	100004(0003)	AT indicator	indicator	Auto-tuning indicator	0: OFF 1: ON	-	-
- 1	100005(0004)	AL1 indicator		Alarm output 1 indicator	0: OFF 1: ON	-	-
	100006(0005)	AL2 indicator		Alarm output 2 indicator	0: OFF 1: ON	-	-
أان	100006 to 100050	Reserved					

2-3. Read Input Registers (Func 04) [Func:02, R/W: R]

No.(Address)	Туре		Description	range	Unit	Default
300001 to 300100	Reserved			1 - 5 -		
300101(0064)	-		Product number H	-	-	Dedicate
300102(0065)	-		Product number L -		-	model number
300103(0066)	-		Hardware version	-	-	
300104(0067)	-		Software version	-	-	
300105(0068)	-		Model 1	-	-	"TX"
300106(0069) -			Model 2	-	-	" 4"
300107(006A)	-		Model 3	-	-	"S "
300108(006B)	-		Model 4	-	-	"14"
300109(006C)	-		Model 5	-	-	"R "
300110(006D)	-		Model 6	-	-	" "
300111(006E)	-		Model 7	-	-	
300112(006F)	-		Model 8	-	-	
300113(0070)	-		Model 9	-	-	
300114(0071)	-		Model 10	-	-	
300115(0072)	-		Reserved	-	-	-
300116(0073)	-		Reserved	-	-	-
300117(0074)	-		Reserved	-	-	-
300118(0075)	-		Coil status start address	-	-	0000
300119(0076)	-		Coil status quantity	-	-	0
300120(0077)	-		Input status start address	-	-	0000
300121(0078)	-		Input status quantity	-	-	0
300122(0079)	-		Holding register start address -		-	0000
300123(007A)	-		Holding register quantity	-	-	0
300124(007B)	-		Input register start address -		-	0000
300125(007C)	-		Input register quantity	-	-	0
300127 to 300200	Reserved					
301001(03E8)	PV		Present value	-1999 to 9999	°C/°F	-
301002(03E9)	DOT		Decimal point location	0:0, 1:0.0, 2:0.00, 3:0.000	-	-
301003(03EA)	UNIT		Display unit	0: °E, 1: °F	-	-
301004(03EB)	SV		Setting value	Within L - 51 to H - 51	°C/°F	0
	°C indicator		Unit indicator	0: OFF 1: ON	-	-
	°F indicator		Unit indicator	0: OFF 1: ON	-	-
301005(03EC)	OUT indicator	Front	Control output indicator	0: OFF 1: ON	-	-
JU IUUJ(UJEU)	AT indicator	indicator	Auto-tuning indicator	0: OFF 1: ON	-	-
	AL1 indicator		Alarm output 1 indicator	0: OFF 1: ON	-	-
	AL2 indicator		Alarm output 2 indicator	0: OFF 1: ON	-	-
310006 to 310050	Reserved					

Preset Multiple Registers (Func 16)[Func:03/06/16, R/W : R/W]

2-4-1. SV setting No.(Address)

No.(Address)	Parameter		Description		Setting/Display range	Unit	Default
100001(0000)	Set value		SV setting value		Within L - 51 to H - 51	°C/°F	0
100002 to 400050	0002 to 400050 Reserved						
-4-2. Parameter 1 group [PAR ।]							
o.(Address) Parameter Description Setting/Display range Unit Default					Default		
100051(0032)	AL I	AL1 ten	nperature Deviation temperature: -F.S. to F.S.				

Ш	No.(Address)	Parameter	Description	Setting/Display range	Unit	Default
$\exists 1$	400051(0032)	AL I	AL1 temperature	ture Deviation temperature: -F.S. to F.S.		1250
Ш	400052(0033)	AL2	AL2 temperature	Absolute value alarm: Temperature range	°C/°F	1620
Ш	400053(0034)	ЯŁ	Auto-tuning	0: oFF 1: oN	-	oFF
Ш	400054(0035)	Р	Proportional band	1 to 9999: 0. / to 999.9	°C/°F	10.0
Ш	400055(0036)	;	Integral time	0 to 9999: 0 to 9999	Sec	0
ا∟	400056(0037)	d	Derivative time	0 to 9999: 0 to 9999	Sec	0
- 1	400057(0038)	RESE	Manual reset	0 to 1000: 0.0 to 100.0	%	5 0.0
- 1	400058(0039)	НУ5	Hysteresis	1 to 100(1 to 500): 1 to 100 (0.1 to 50.0)	-	2
- 1	400059 to 400100	Reserved				

2-4-3. Parameter 2 group [PRR2]

No.(Address)	Parameter	Description	Setting/Display range	Unit	Default	
400101(0064)	IN-E	Input sensor	Refer to '■ Input Type And Range'	-	KERH	
400102(0065)	UNI E	Temperature unit	0: ºE, 1: ºF	-	٥٤	
400103(0066)	IN-b	Input correction	-999 to 999(-1999 to 9999): -999 to 999(-1999 to 9999)	-	0	
400104(0067)	MAV,F	Input digital filter	1 to 1200: 0. I to I20.0	Sec	0.1	
400105(0068)	L-51	SV low-limit value	Defects III Insect Time And December	°C /°F	-50	
400106(0069)	H-51	SV high-limit value	Refer to '■ Input Type And Range'	°C/°F	1500	
400107(006A)	o-Ft	Control output mode	O: HERE, 1: Cool	-	HERE	
400108(006B)	[-Md	control method	0: PI d, 1: oNoF	-	PI d	
400109(006C)	oUt	Control output selection	0: 55R, 1: EURR	-	CURR	
400110(006D)	55RM	SSR drive output method	0: 5 E N d , 1: C Y C L , 2: P H R S	-	5 E N d	
400111(006E)	o.MR	Current output range	0: 4-20, 1: 0-20	-	4-20	
400112(006F)	E	Control cycle	5 to 1200: 0.5 to 1200	Sec	2 [],[](Relay) 2,[](SSR drive)	
400113(0070)	RL-I	AL1 operation	00: AMO , 10 to 15: AM IA to AM IF ,		AM LA	
400114(0071)	AL-2	AL2 operation	60 to 65: RMER to RMEF, 70: SERR, 71: SERE, 80: LERR, 81: LERE	-	Am2.A	
400115(0072)	RHYS	Alarm output hysteresis	1 to 100(1 to 500): 1 to 100 (0.1 to 50.0)	-	1	
400116(0073)	LbRE	LBA detection time	0 to 9999: 🛭 to 9999	Sec	0	
400117(0074)	LbRb	LBA detection band	0 to 999(0 to 9999): 0 to 999(0.0 to 999.9)	°C/°F	2	
400118(0075)	F5-L	Trans. output low- limit value	Refer to '■ Input Type And Range'.	-	- 50	
400119(0076)	F5-H	Trans. output high- limit value	Relei to I input Type And Range .	-	1500	
400120(0077)	RdRS	Com. address	1 to 127: 1 to 127	-	1	
400121(0078)	ьP5	Com. speed	0: 24, 1: 48, 2: 95, 3: 192, 4: 384	-	96	
400122(0079)	PRES	Com. parity bit	0: NoNE , 1: EVEN , 2: odd	-	NoNE	
400123(007A)	SEP	Com. stop bit	0: 1, 1: ₹	-	2	
400124(007B)	RSWF	Com. response waiting time	5 to 99: 5 to 99	ms	20	
400125(007C)	CoMW	Com. write	0: ENA, 1: d1 5.A	-	ENA	
400126(007D)	d1 - K	Digital input key	0: off, 1:5toP, 2:ALRE, 3:At	-	StoP	
400127(007E)	E R.MV	Control output MV for input break	0 to 1000: @@(OFF) to 1000(ON)	%	0.0	
400128(007F)	LoC	Lock	0:oFF, 1:Lo[1, 2:Lo[2, 3:Lo[3	-	oFF	
400129 to 400150	400129 to 400150 Reserved					

Display	Description	Troubleshooting
oPEN .	Flashes when input sensor is disconnected or sensor is not connected.	Check input sensor status.
нннн		When input is within the
LLLL		rated input range, this display disappears.

Parameter 2 group

■ Factory Default

SV setting

Parameter	Factory default		
_	0		

Parameter 1 group			
Parameter	Factory default		
RL I	1250		
RL2	1630		
RE.	oFF		
Р	10.0		
1	п		
d	u u		
RESE	5 0.0		
H95	2		

1 N - E	K E R.H	AH95	1
UNI E	٥٤	LBRE	0
1 N-b	0	L b R b	2
MAV.F	O. 1	F5-L	-50
L-51/	-50	FS-H	1500
H-51/	1500	AGRS	1
o-Ft	HERE	6PS	96
[-Md	PId	PRES	NoNE
oUt	CURR	SEP	2
SSR.M	SENd	RSWE	20
o.MA	4-20	C o M W	E N.A
E	2 ((Relay)	d1 - K	StoP
	2.0 (SSR drive)	E R.MV	0.0
AL-1	AM LA	LoC	oFF
RL-2	AM2,A		

Parameter Factory default Parameter Factory default

Cautions during Use

Follow instructions in 'Cautions during Use'. Otherwise, It may cause unexpected accidents.

Check the polarity of the terminals before wiring the temperature sensor.For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length

For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.

Keep away from high voltage lines or power lines to prevent inductive noise.
 In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

Do not use near the equipment which generates strong magnetic force or high frequency noise.

4. Do not apply excessive power when connecting or disconnecting the connectors of the product.

5. Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.

Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.When changing the input sensor, turn off the power first before changing.

After changing the input sensor, modify the value of the corresponding parameter

Do not overlapping communication line and power line.
 Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect

of external noise. Make a required space around the unit for radiation of heat.

For accurate temperature measurement, warm up the unit over 20 min after turning on the power.

10. Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
11. Do not wire to terminals which are not used.
12. This unit may be used in the following environments.

①Indoors (in the environment condition rated in 'Specifications')

②Altitude max. 2.000m

Major Products

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DRW170771AA